

# Rohan Khatri

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## EDUCATION

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### Texas Tech University (Honors College)

Lubbock, TX

*B.S. Electrical Engineering & Physics, GPA: 3.9/4.0*

*Incoming Junior, Expected Fall 2027*

- Relevant Coursework: Circuit Analysis, Electronics, Signals & Systems, EM Fields, Digital Systems, Embedded Systems, Differential Equations, Probability & Statistics

## EXPERIENCE

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### Hardware Research Engineer (Undergraduate)

March 2025 – August 2025

*Texas Tech Honors College (Funded Research)*

*Lubbock, TX*

- Developed a real-time embedded voice AI system on ESP32 with dual-core FreeRTOS, handling 24kHz audio capture and playback across a 78×700-sample circular buffer.
- Designed and hand-soldered a custom PCB with tiny ESP32 SoC, power management ICs, and audio frontend for low-latency audio streaming.
- Implemented AWS cloud backend using Dockerized Python, WebSocket integration with OpenAI Realtime API, and TCP/UDP streaming for bidirectional audio (<500ms perceived latency).
- Built a companion React Native mobile app with real-time device communication, calendar/email integration, and audio streaming control
- Won social entrepreneurship challenge for assistive technology application with a cash prize

### Undergraduate Research Assistant – UAV Systems

October 2025 – Present

*Texas Tech University*

*Lubbock, TX*

- Assisting in development of a hexacopter platform for GPR-based UXO detection in Ukrainian conflict zones
- Perform flight testing and Pixhawk autopilot configuration using MAVLink telemetry and QGroundControl
- Designed structural components and sensor mounting systems in Fusion 360; fabricated parts via 3D printing
- Conduct PID tuning and flight log analysis to diagnose control issues and optimize autonomous flight stability

## TECHNICAL PROJECTS

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### Gravity-Based Height Measurement Device

*Arduino Mechatronics Project*

- Measured height using free-fall kinematics with laser-photodiode timing

### Autonomous Line-Following Rover

*MSP430 Embedded System*

- Programmed MSP430 in register-level C for PWM motor control and sensor interfacing
- Implemented IR line tracking and ultrasonic obstacle detection with interrupt-driven logic

### DTMF Tone Decoder

*Digital Signal Processing*

- Implemented FFT-based dual-tone detection and frequency classification in Python with 95% accuracy

### Published Mobile Applications

*Software Engineering*

- Developed and published 4 Android applications including a cloud-based real-time scheduling system for TTU with 150+ test users

## TECHNICAL SKILLS

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**Embedded Systems:** C, C++, Object-Oriented Programming (OOP), Python, Matlab, FreeRTOS, Register-Level C, LTSpice

**Hardware:** PCB Design, PCBA, ESP32/MSP430, Signal Conditioning, Lab Equipment

**Control:** PID Tuning, MAVLink, Pixhawk/QGroundControl, Sensor Integration

**Tools:** Autodesk Fusion 360, KiCad, 3D Printing, CNC workflows, AWS IoT, Docker, Git